

```
> dgl:=diff(y(x),x)=y(x);
```

$$dgl := \frac{\partial}{\partial x} y(x) = y(x)$$

```
> dgl;
```

$$\frac{\partial}{\partial x} y(x) = y(x)$$

```
> dsolve(dgl);
```

$$y(x) = _C1 e^x$$

```
> dgl:=D(y)(x)=y(x);
```

$$dgl := D(y)(x) = y(x)$$

```
> dsolve(dgl);
```

$$y(x) = _C1 e^x$$

```
> dsolve({dgl,y(0)=3},y(x));
```

$$y(x) = 3 e^x$$

```
> dgl:=diff(y(x),x)=y(x)-y(x)^2;
```

$$dgl := \frac{\partial}{\partial x} y(x) = y(x) - y(x)^2$$

```
> dgl;
```

$$\frac{\partial}{\partial x} y(x) = y(x) - y(x)^2$$

```
> dsolve(dgl);
```

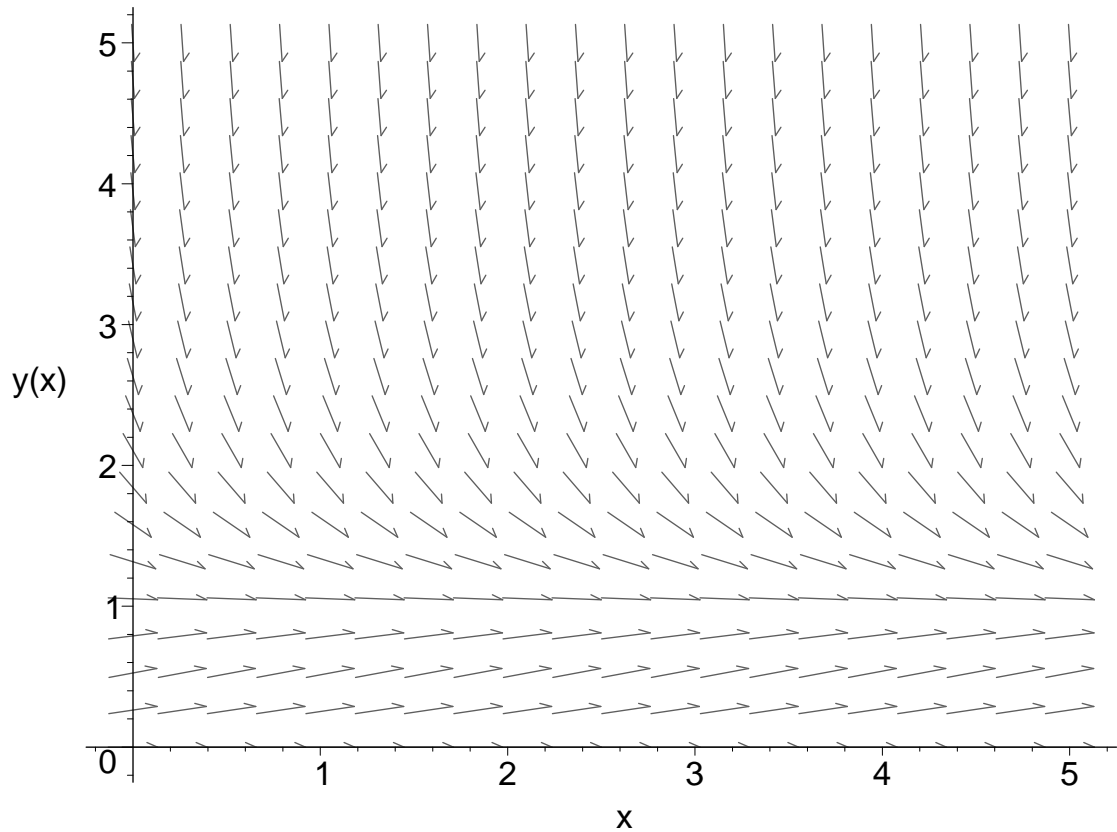
$$y(x) = \frac{1}{1 + e^{(-x)} _C1}$$

```
> with(DEtools);
```

```
[DENormal, DEplot, DEplot3d, DEplot_polygon, DFactor,
```

DfactorLCLM, DFactorsols, Dchangevar, GCRD, LCLM, MeijerGsols, PDEchangecoords, RiemannPsols, Xchange, Xcommutator, Xgauge, abelsol, adjoint, autonomous, bernoullisol, buildsol, buildsym, canoni, caseplot, casesplit, checkrank, chinisol, clairautsol, constcoeffsols, convertAlg, convertsys, dalembertsol, dcoeffs, de2diffop, dfieldplot, diffop2de, dpolyform, dsubs, eigenring, endomorphism_charpoly, equinv, eta_k, eulersols, exactsol, expsols, exterior_power, firint, firtest, formal_sol, gen_exp, generate_ic, genhomosol, gensys, hamilton_eqs, hypergeomsols, hyperode, indicialeq, infgen, initialdata, integrate_sols, intfactor, invariants, kovacicsols, leftdivision, liesol, line_int, linearsol, matrixDE, matrix_riccati, maxdimsystems, moser_reduce, muchange, mult, mutest, newton_polygon, normalG2, odeadvisor, odepde, parametricsol, phaseportrait, poincare, polysols, ratsols, redode, reduceOrder, reduce_order, regular_parts, regularsp, remove_RootOf, riccati_system, riccatisol, rifread, rifsimp, rightdivision, rtaylor, separablesol, solve_group, super_reduce, symgen, symmetric_power, symmetric_product, symtest, transinv, translate, untranslate, varparam, zoom]

> DEplot (dg1 , y (x) , x=0 . . 5 , y=0 . . 5) ;



```
> p2:=DEplot(dgl,y(x),x=0..5,y=0..5):
> dsolve({dgl,y(1)=4},y(x));
```

$$y(x) = \frac{1}{1 - \frac{3 e^{(-x)}}{4 e^{(-1)}}$$

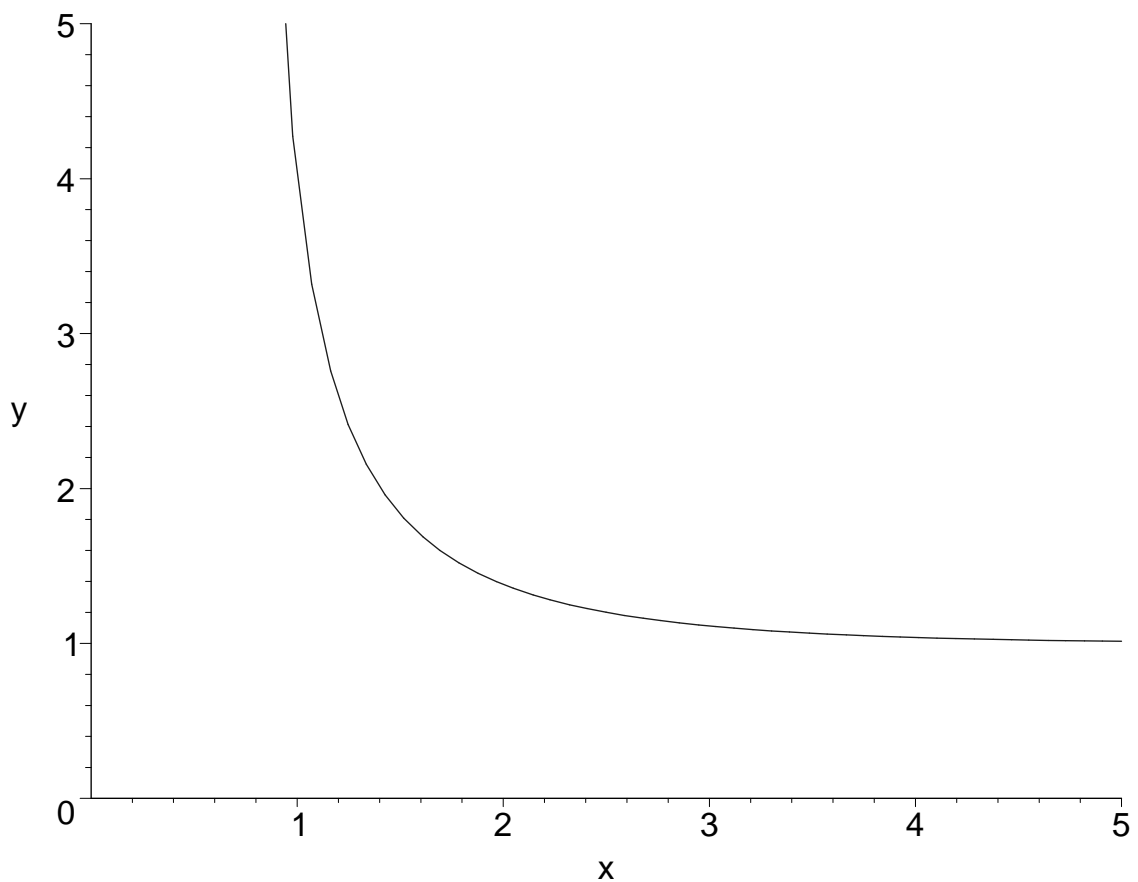
```
> f:=rhs(%);
```

$$f := \frac{1}{1 - \frac{3 e^{(-x)}}{4 e^{(-1)}}$$

```
> f;
```

$$\frac{1}{1 - \frac{3e^{(-x)}}{4e^{(-1)}}$$

```
> plot(f(x),x=0..5,y=0..5,discont=true,color=blue);
```

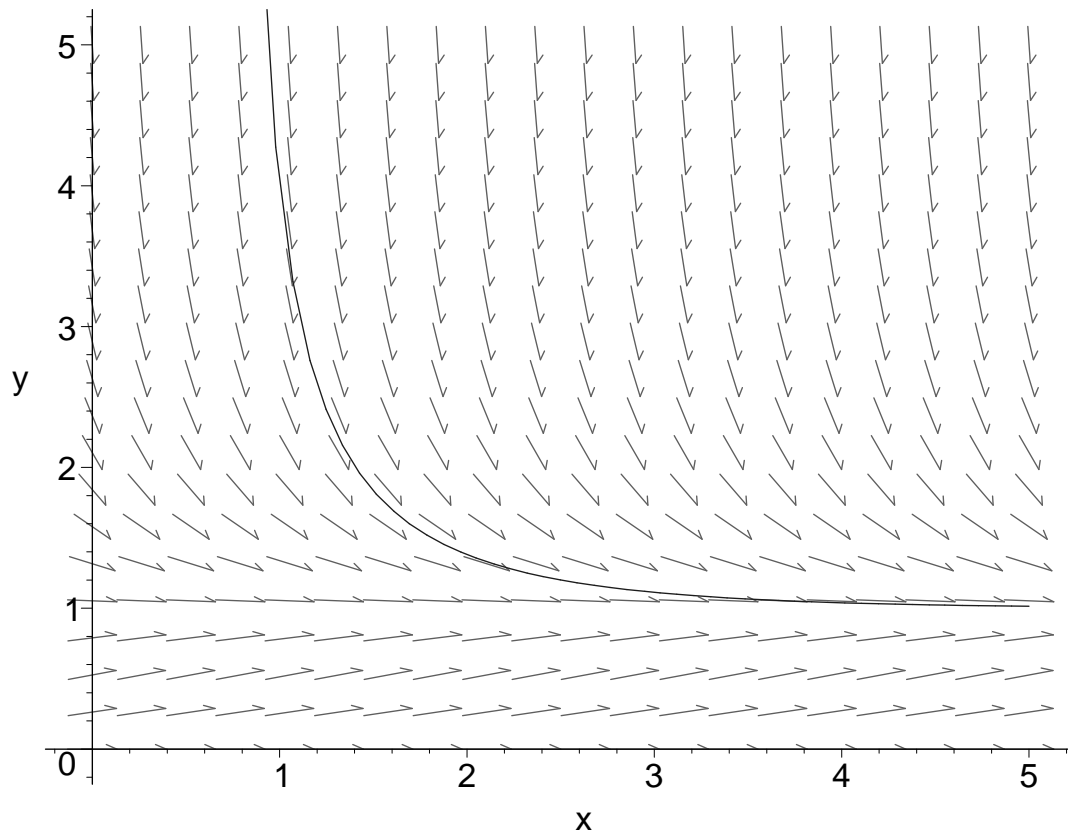


```
> p1:=plot(f(x),x=0..5,y=0..5,discont=true,color=blue):
```

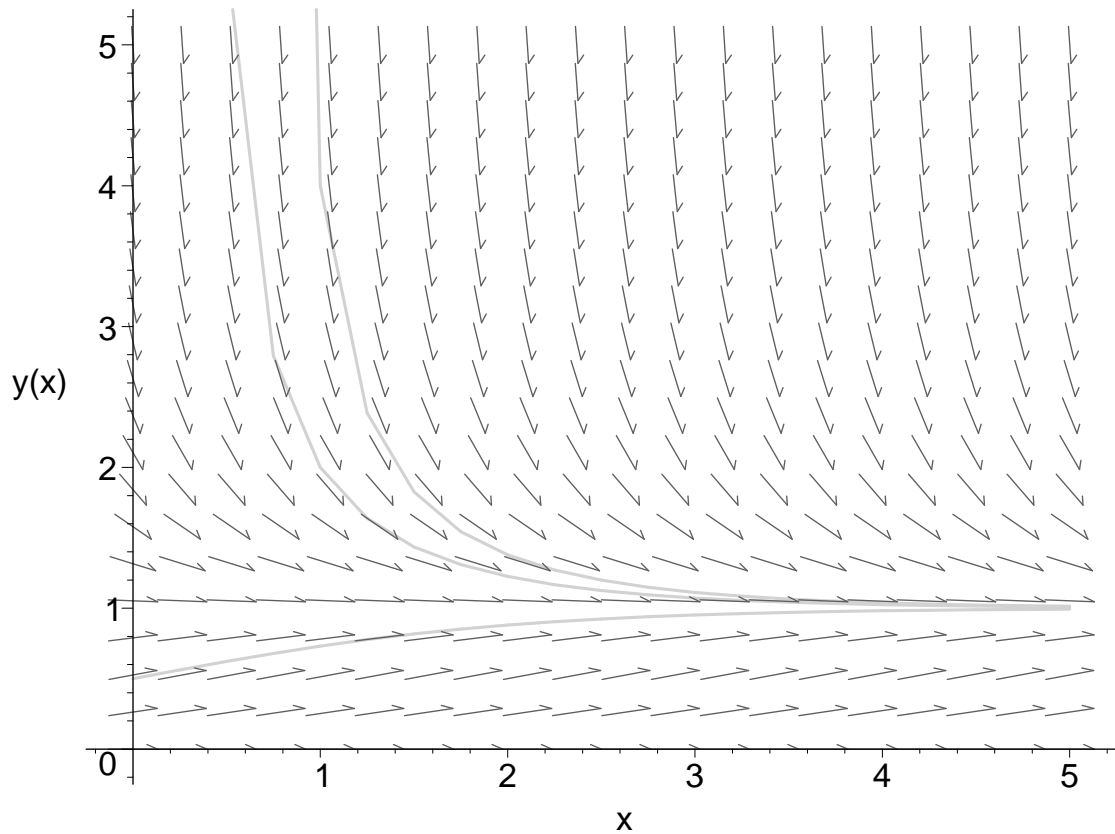
```
> with(plots):
```

```
Warning, the name changecoords has been redefined
```

```
> display({p1,p2});
```



```
> DEplot(dgl, y(x), x=0..5, y=0..5, [[y(1)=4], [y(1)=2], [y(0)=1/2]]);
```



```
> dgl:=diff(x(t),t,t)+2*diff(x(t),t)+17*x(t)=0;
```

$$dgl := \left(\frac{\partial^2}{\partial t^2} x(t) \right) + 2 \left(\frac{\partial}{\partial t} x(t) \right) + 17 x(t) = 0$$

```
> dgl;
```

$$\left(\frac{\partial^2}{\partial t^2} x(t) \right) + 2 \left(\frac{\partial}{\partial t} x(t) \right) + 17 x(t) = 0$$

```
> dsolve(dgl);
```

$$x(t) = _C1 e^{(-t)} \sin(4 t) + _C2 e^{(-t)} \cos(4 t)$$

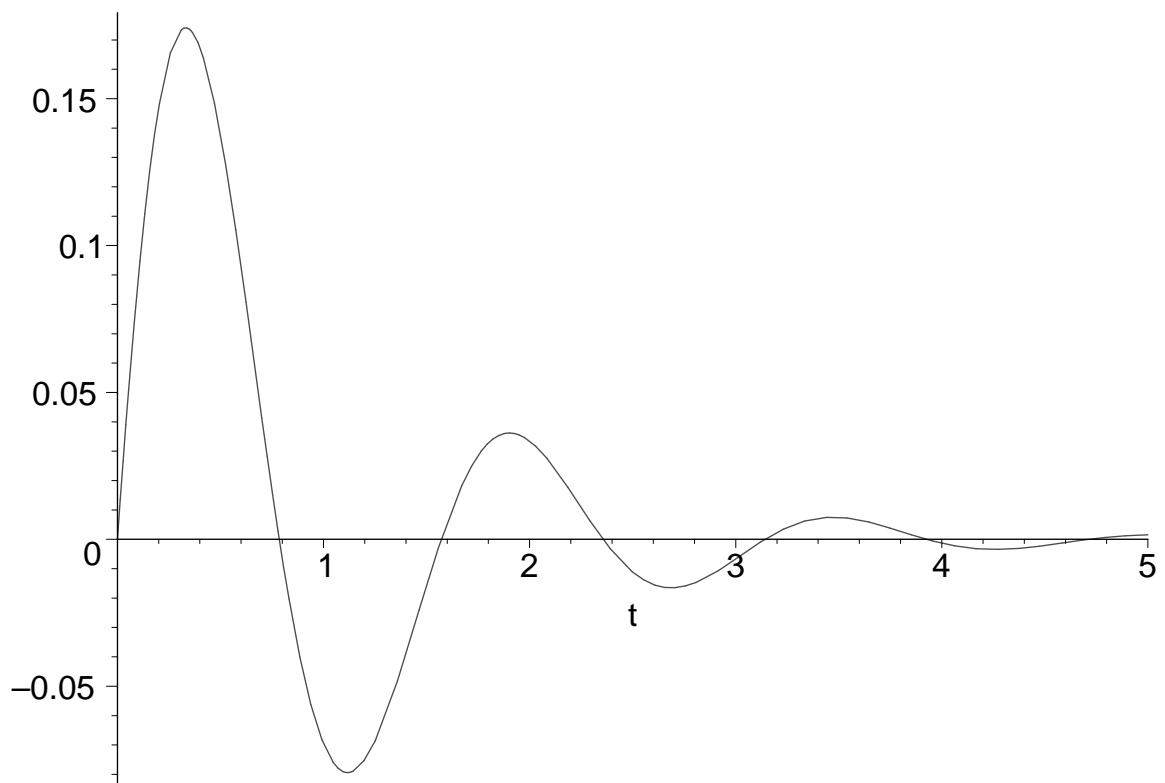
```
> dsolve({dgl,x(0)=0,D(x)(0)=1},x(t));
```

$$x(t) = \frac{1}{4} e^{(-t)} \sin(4t)$$

```
> f:=rhs(%);
```

$$f := \frac{1}{4} e^{(-t)} \sin(4t)$$

```
> plot(f, t=0..5);
```



```
> dgl:=diff(x(t),t,t)+2*diff(x(t),t)+17*x(t)=  
cos(t);
```

$$dgl := \left(\frac{\partial^2}{\partial t^2} x(t) \right) + 2 \left(\frac{\partial}{\partial t} x(t) \right) + 17 x(t) = \cos(t)$$

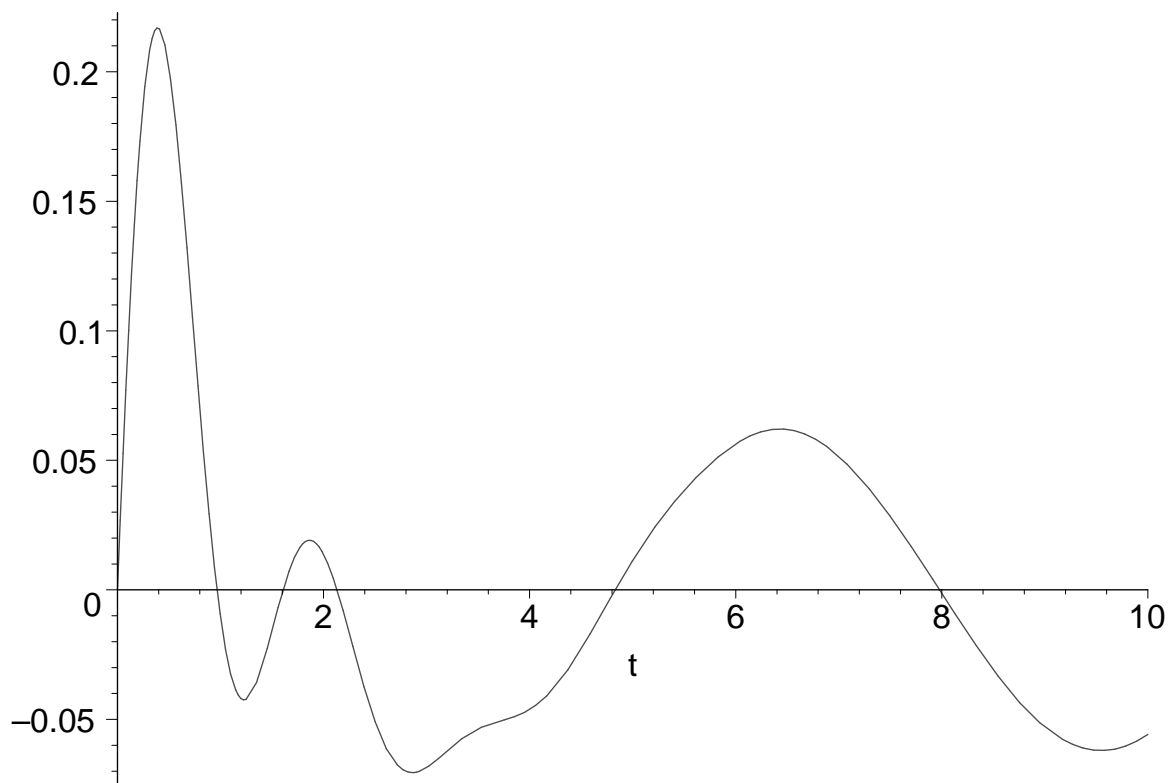
```
> dsolve( {dgl, x(0)=0, D(x)(0)=1}, x(t) );
```

$$x(t) = \frac{121}{520} e^{(-t)} \sin(4t) - \frac{4}{65} e^{(-t)} \cos(4t) + \frac{4}{65} \cos(t) + \frac{1}{130} \sin(t)$$

> f:=rhs(%);

$$f := \frac{121}{520} e^{(-t)} \sin(4t) - \frac{4}{65} e^{(-t)} \cos(4t) + \frac{4}{65} \cos(t) + \frac{1}{130} \sin(t)$$

> plot(f, t=0..10);



> dgl:=diff(x(t),t,t)+sin(x(t))=0;

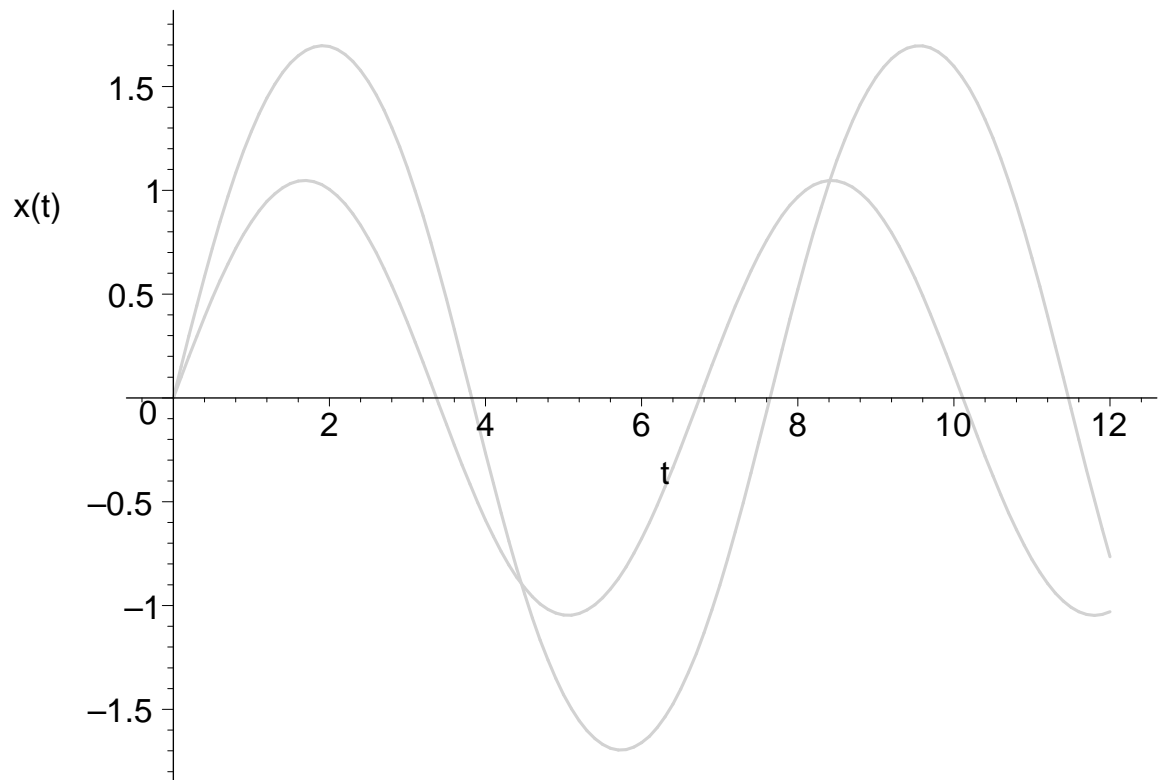
$$dgl := \left(\frac{\partial^2}{\partial t^2} x(t) \right) + \sin(x(t)) = 0$$

> dsolve(dgl);

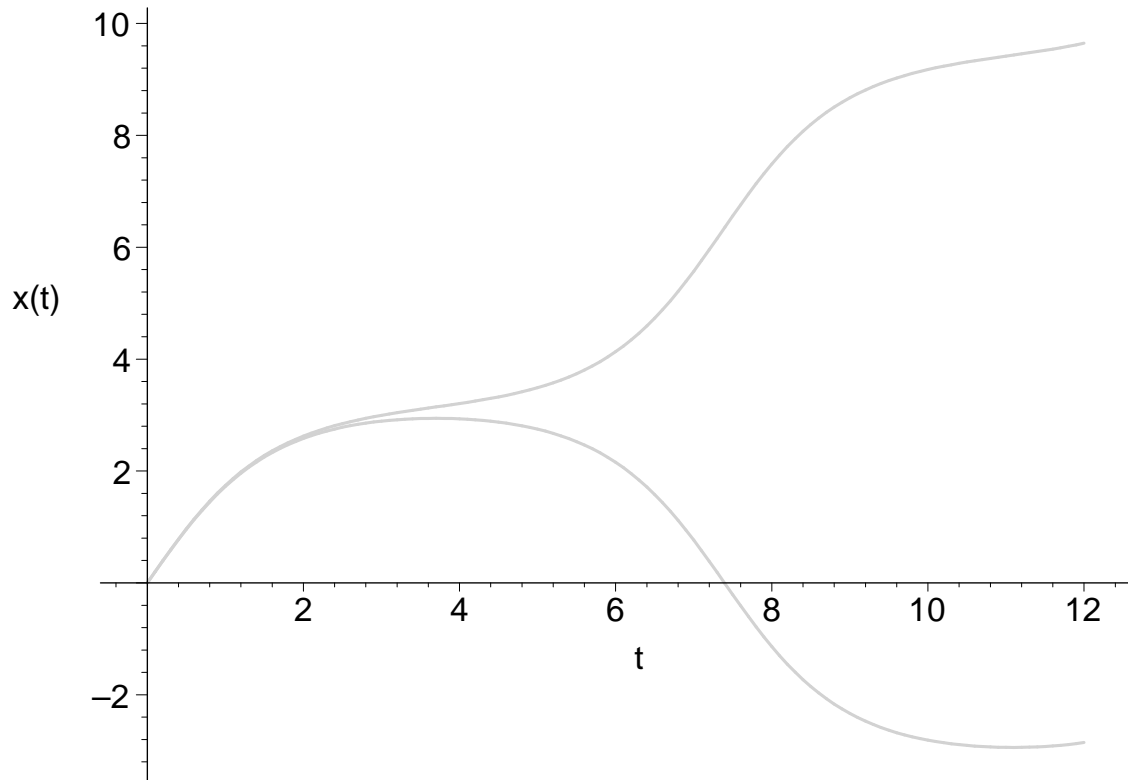
$$\int_{-x(t)}^{x(t)} -\frac{1}{\sqrt{2 \cos(_a) + _C1}} d_a - t - _C2 = 0,$$

$$\int_{-x(t)}^{x(t)} \frac{1}{\sqrt{2 \cos(_a) + _C1}} d_a - t - _C2 = 0$$

```
> DEplot(dgl, x(t), t=0..12, [[x(0)=0, D(x)(0)=1],
, [x(0)=0, D(x)(0)=1.5]], stepsize=0.1);
```



```
> DEplot(dgl, x(t), t=0..12, [[x(0)=0, D(x)(0)=2.01],
, [x(0)=0, D(x)(0)=1.99]], stepsize=0.1);
```



```
> dgl:= [diff(x(t),t)=x(t)*(a-b*y(t)),diff(y(t),t)=y(t)*(-c+d*x(t))];
```

$$dgl := \left[\frac{\partial}{\partial t} x(t) = x(t)(a - b y(t)), \frac{\partial}{\partial t} y(t) = y(t)(-c + d x(t)) \right]$$

```
> a:=3;b:=2;c:=2;d:=1;
```

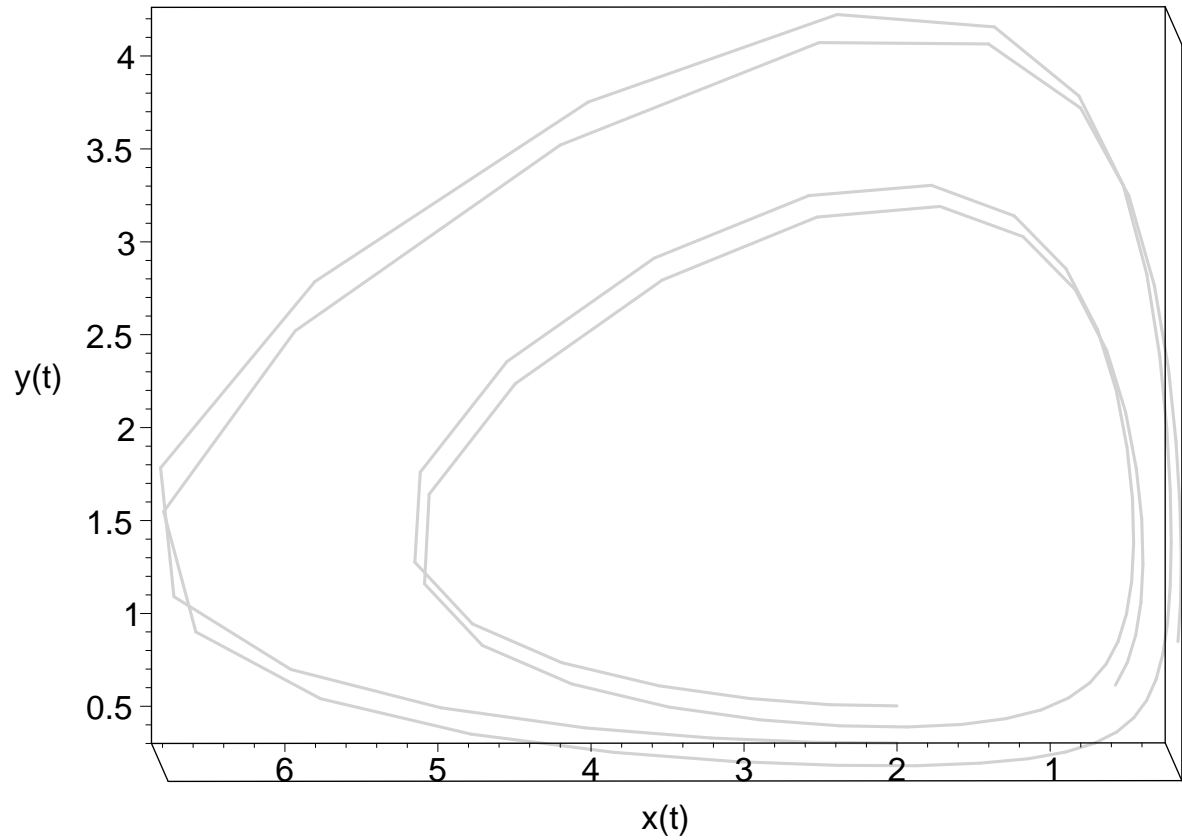
```
      a:=3
```

```
      b:=2
```

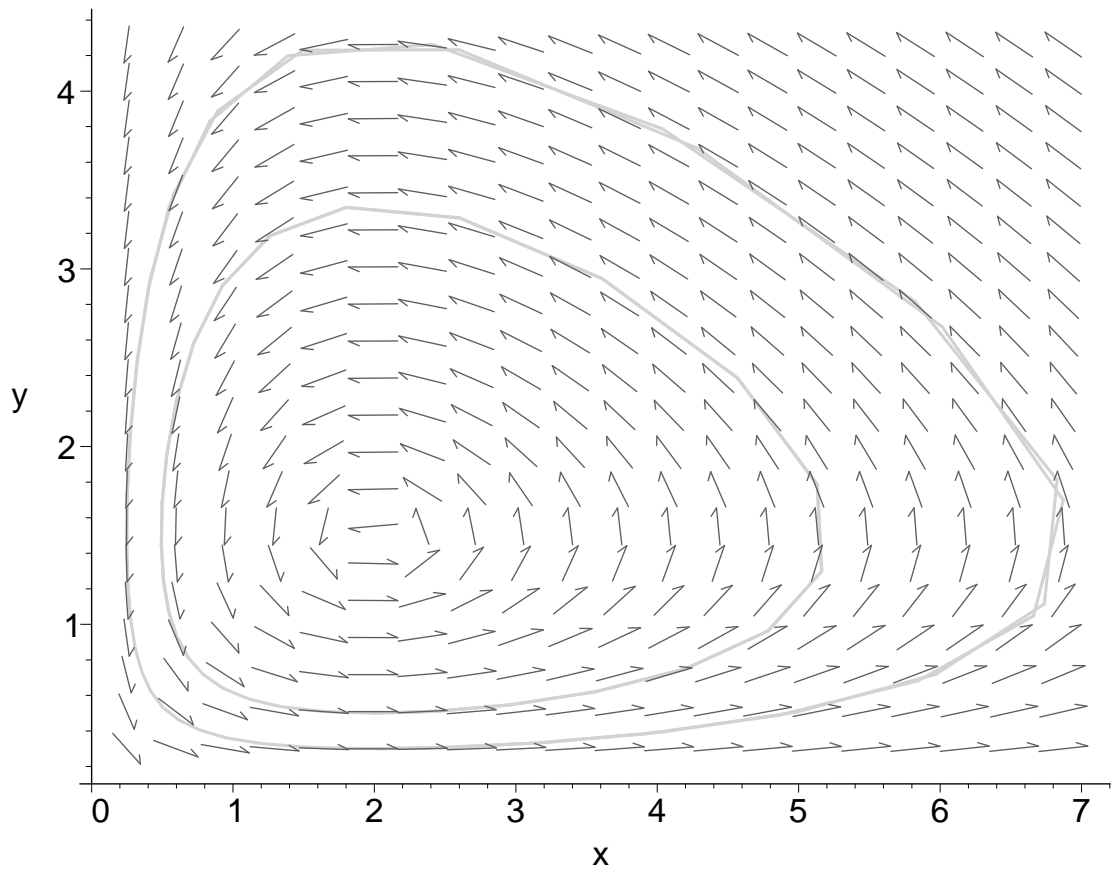
```
      c:=2
```

```
      d:=1
```

```
> DEplot3d(dgl,[x(t),y(t)],t=0..5,[[x(0)=2,y(0)=0.3],[x(0)=2,y(0)=0.5]],stepsize=0.1);
```



```
> DEplot(dgl,[x(t),y(t)],t=0..5,[[x(0)=2,y(0)
=0.3],[x(0)=2,y(0)=0.5]],stepsize=0.1);
```



[>